

# Alexander Uamai | BSc Mechatronic Systems Engineering

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## WORK EXPERIENCE

### Pipeline Technical Developer Intern — *Digital Domain*

JAN 2022 – APR 2022, VANCOUVER, BC

- Collaborated with Digital Domain's Character Effects (CFX) department, contributing significantly to key project initiatives.
- Executed a seamless migration of pipeline tools from Python 2 to Python 3, aligning them with the latest industry standards.
- Conducted thorough testing and debugging of Python-based pipeline tools, resulting in substantial enhancements to tool reliability and stability.

### Manufacturing Engineering Intern — *VMAC Air*

SEP 2021 – DEC 2021, NANAIMO, BC

- Designed enclosure and components for a novel air compressor test bench, showcasing proficiency in SolidWorks.
- Developed a web-based interface for monitoring data from the compressor test bench; parsed JSON data to generate informative charts and graphs illustrating test throughput.
- Ensured manufacturing quality by meticulously reviewing engineering drawings, guaranteeing compliance with standards and passing rigorous quality checks.

### Software Engineering Intern — *Ziva Dynamics*

MAY 2021 – AUG 2021, VANCOUVER, BC

- Engineered a groundbreaking tool enabling VFX artists to submit and render scenes on cloud computers directly from within Maya.
- Developed a robust menu bar and toolbar for Ziva's VFX 2.0 Maya plug-in using PySide enhancing the user interface for seamless navigation and increased efficiency.
- Transitioned Ziva's simulator cache mechanism to an alternative solution, resulting in accelerated character simulation and improved overall performance.

### Information Technology Intern — *Mulgrave School*

JAN 2021 – MAY 2021, WEST VANCOUVER, BC

- Delivered exceptional Level 1 technical support, offering expert guidance to students and staff, swiftly resolving queries and technical issues.
- Pioneered the deployment of OctoPi on Raspberry Pi devices, significantly enhancing 3D printing capabilities at the school.
- Designed and fabricated custom enclosures for Raspberry Pi cameras, mounting them on 3D printers for remote monitoring and real-time monitoring, showcasing practical IT skills and creativity.

## ENGINEERING DESIGN TEAM

### Alivio Technologies — *Controls Lead*

- Led controls development for "Lief", a groundbreaking wearable designed to alleviate foot dystonia discomfort.
- Engineered firmware to manage dual coin-type vibration motors within a foot wrap, enhancing user experience.
- Conducted hands-on assembly, soldering the vibration system onto a protoboard for seamless integration with the device.

## EDUCATION

### Simon Fraser University

SEPTEMBER 2018 – AUGUST 2023

BASc Mechatronic Systems Engineering

Deans Honour Roll Spring and Summer 2023

## TECHNICAL SKILLS

### Languages

C, C++, Python

### Tools

Git, GitHub, Jira, MATLAB, Simulink, SolidWorks, Oscilloscope, Linux

### Other

UART, I2C, SPI, STM32, Arduino, Raspberry Pi, Qt, GD&T, DFM, CAD

## PROJECTS

### Dynamic Motion Interface for Game Control

STM32F407VG, C, Python, SPI, USB  
Engineered firmware in C for an STM32 microcontroller to enable dynamic motion control in a 2D desktop game. Developed SPI drivers to establish communication between the microcontroller and the accelerometer. Implemented timers and interrupts for efficient streaming of sensor data to the game through USB.

### Design and Control of a Two-Wheeled Self-Balancing Robot

Matlab, Simulink, Simscape, State-SpaceModeling  
Designed a feedback control system for a two-wheeled self-balancing robot using Matlab, and Simulink, employing state-space methods for system dynamic analysis, controllability, and observability to achieve stable balancing. Developed a visual simulation of the robot using Simscape.

### Wind Energy Conversion System Design

Matlab, Simulink, Power Electronics, Control Systems  
Led the design of a wind energy conversion system, utilizing Matlab and Simulink for modeling and optimization of control strategies, power conversion, and system performance. Delivered a detailed report covering theoretical analysis, calculations, and simulation results under varying conditions.